

Estimating Uncertainty in Fishing Effort Estimates Using Bootstrapping with a Two-Stage Model

A Senior Project
Presented to
The Faculty of the Statistics Department
California Polytechnic State University, San Luis Obispo

In Partial Fulfillment
Of the Requirements for the Degree
Bachelor of Science, Statistics

By:
Samantha Dellinger
June 2014

Table of Contents

| | |
|--|-----------|
| I. Introduction | 3 |
| A. Background | 3 |
| B. The Data | 3 |
| C. Analytics | 5 |
| III. Tools for Analysis | 6 |
| A. Kernel Density Estimation to Estimate Drop Densities | 6 |
| B. Generalized Additive Model to Smooth Effort Estimations | 11 |
| C. Two-Stage Bootstrapping to Estimate Fishing Effort and Variability of Estimates | 15 |
| IV. Results | 17 |
| A. Estimation of Effort (KDE and Splines) | 17 |
| B. Estimation of Variability (Bootstrapping) | 21 |
| C. Annual Effort Pre and Post MPA | 25 |
| D. Limitations | 26 |
| V. Appendix | 27 |
| A. R Code | 27 |
| B. Record of Hours | 39 |
| VI. Works Cited | 42 |

I. Introduction

A. Background

In 2007, in hopes of protecting the two species of fish rockfish and lingcod, the government implemented marine protected areas (or mpa's), in the South Central Coast. In these protected areas shown in Figure 1,¹ the capabilities of the captains that lead the party boat fishing trips were limited, which raised the question of how the fishing has changed since the marine protected areas were put in place. It is a common hypothesis that the fisherman will fish on the edge of the specified marine protected areas, in hopes that fishing extremely close to the protected areas will lead to them catching bigger and better fish.

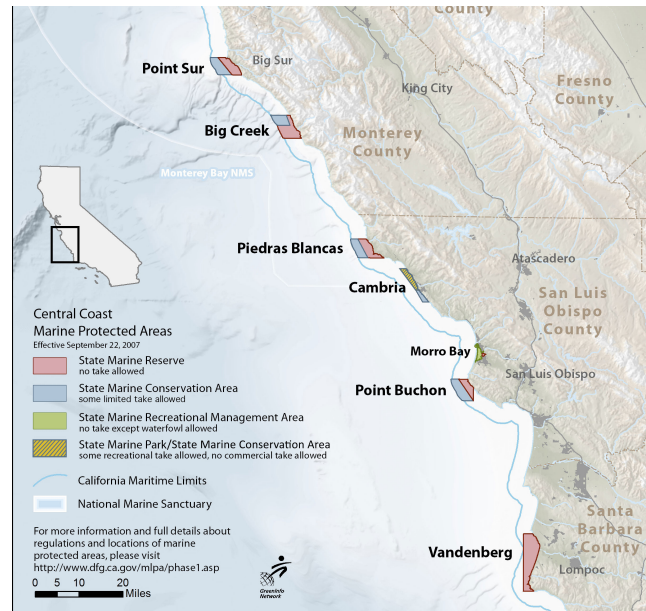


Figure 1: Map of the Central Coast

Party boat fishing consists of a captain, who owns a commercial passenger fishing vessel, being paid to take others on an agreed upon number of trips, or until all of the people on the vessel have reached their bag limit (the legal maximum number fish an individual can catch). For the South Central Coast, these fishing trips come out of Morro Bay and Port San Luis, and are primarily booked through Virg's Sport Fishing, Patriot Sport Fishing, and Central Coast Sport Fishing.

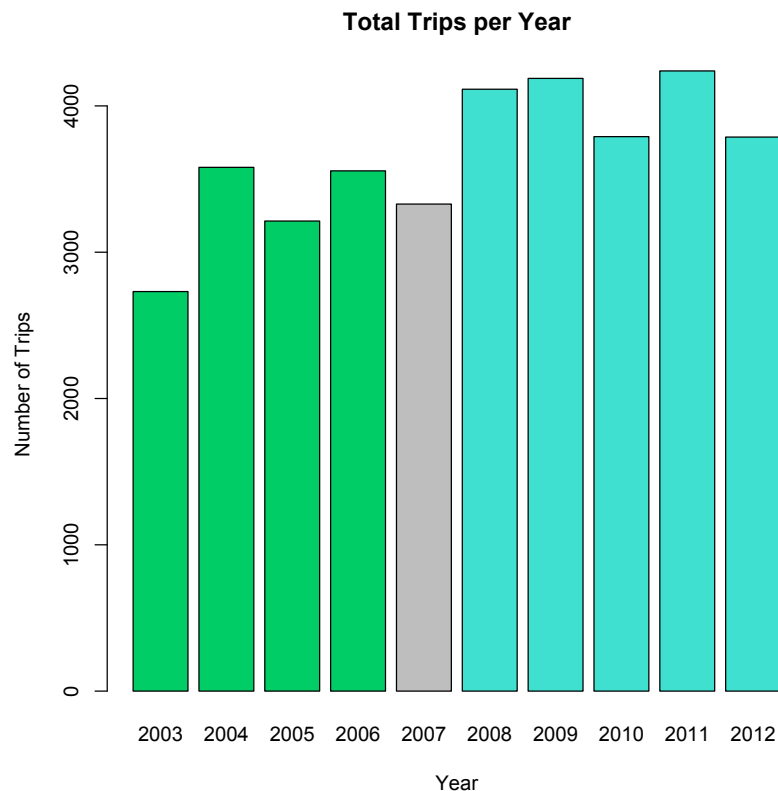
B. The Data

When Dr. Andrew Schaffner and I met with Biology grad student Morgan Ivens-Duran for the first time, she came to us with a data set that included information pertaining to party boat fishing on the South Central Coast of California that covered eleven past years. This data collection began in 2003, when Morgan's lab, the Center for Coastal Marine Sciences, became interested in where fisherman on the South Central Coast were fishing, and how the rockfish and lingcod cohabitate. As natural in a sample, this data set included

¹ California Marine Protected Areas, *Central Coast MPA Region*, <http://www.californiampas.org/pages/regions/centralcoast.html> (January 2014).

information on a small proportion of the boat trips that were made each year, only about 6 to 22 percent. For each trip that was sampled, we have information on three variables: the latitude and longitude of every drop that was made, and the effort that was made at each drop (cumulative time per drop that all fishing lines are in the water).

In 2007, the marine protected areas were put in place, and as a result, the data is split into pre-mpa data from 2003-2006, and post-mpa data from 2008-2012. For the purpose of our analyses, we will leave out the year 2007 because it was the year that the marine protected areas were put in place, and thus has mixed pre and most mpa data. Below, Figure 2 shows a bar graph of the total number of trips that were made per year, showing the divide between pre-mpa years (green) and post-mpa year (blue) with 2007 as a buffer year in gray.



**Figure 2: Bar Graph of Total Trips Made per Year
(Appendix lines 285-295)**

Pre and Post MPA data can be compared to investigate how the spatial pattern and intensity of fishing effort had changed in the South Central Coast region over the 10 year time period, and specifically how it has changed as a result of the implementation of the marine protected areas.

C. Analytics

In order to assist Morgan in exploring her research question, we created estimates of the fishing effort along the Central Coast for each year, allowing her to get a clear picture of where the most effort was located. Furthermore, we provide estimates of the uncertainty in our effort estimates along the Central Coast. To do this we applied several estimation techniques to the data including Kernel Density Estimation and Splines to estimate effort, and Bootstrapping to estimate the uncertainty in our estimates.

The Kernel Density estimation will allow us to estimate the spatial distribution (density) of drops to gain a better understanding of where the fisherman are fishing and how often. In addition to where and how often these fisherman were fishing, we needed to also include the amount of effort that was being put forth each time fishing lines were dropped at each location. We estimated the effort using two-dimensional splines. Finally, to estimate the variability (uncertainty) of these estimates we used bootstrapping. This process was repeated separately for each of the 10 years of pre-mpa and post-mpa data to create a clear picture could be drawn about how the fishing location effort changes from year to year.

III. Tools for Analysis

A. Kernel Density Estimation to Estimate Drop Densities

Kernel Density Estimation is a nonparametric way to estimate the probability density of a random variable. In the simplest terms, Kernel Density Estimation is a density smoother calculated using a weighted moving average. This concept applies really well to a simple histogram: for a set value of x , we compute the (scaled by bandwidth) proportion of the data that falls within a specific neighborhood (determined by the bandwidth) of x . To illustrate this idea, we can first look at the definition of the pdf, $f(x)$, of a random variable X ,

$$P(x - b < X < x + b) = \int_{x-b}^{x+b} f(t)dt \approx 2b f(x),$$

and thus,

$$f(x) \approx \frac{1}{2b} P(x - b < X < x + b)$$

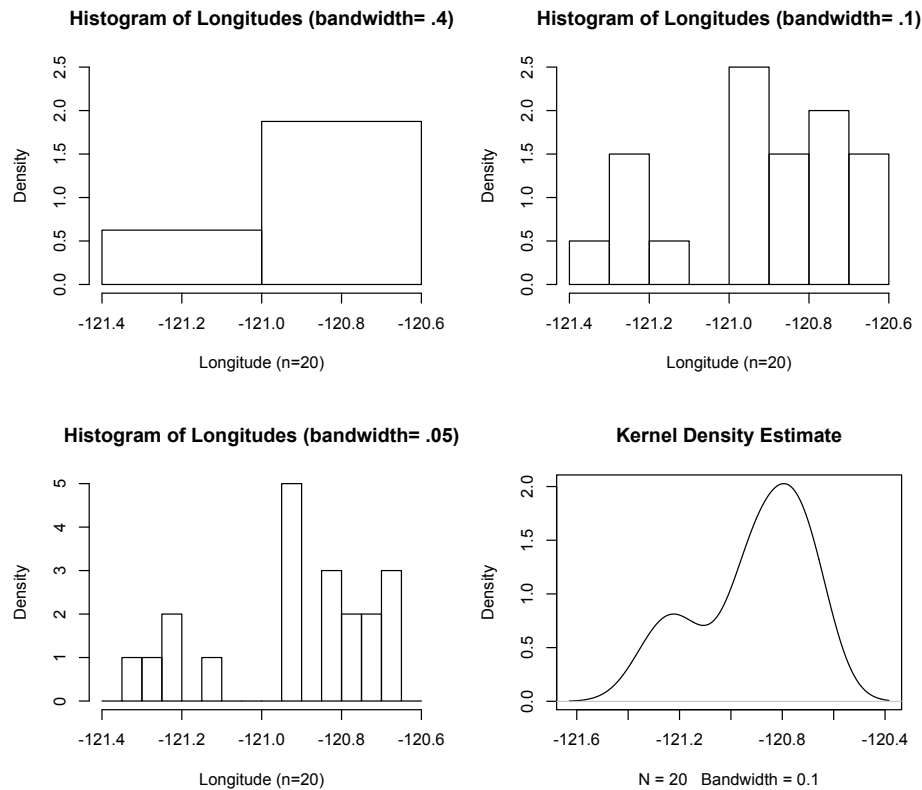
where b represents the bandwidth parameter². This probability can also be estimated by a frequency in the sample, so

$$\hat{f}(x) = \frac{1}{2b} \frac{\text{number of observations in } (x - b, x + b)}{n} .^3$$

The selection of the bandwidth, b , will have a significant effect on the kernel density estimations; choosing a b too large will result in an overly smooth and non descriptive curve, whereas choosing a b that is too small will result in a highly irregular and overly specific smoothing curve. The following histograms in Figure 3 are of a sample of 20 longitude values modeled with different values of b , and a possible kernel density estimate curve using the bandwidth $b=0.1$.

² Walter Zucchini, *Part I: Kernel Density Estimation*, Applied Smoothing Techniques, http://isc.temple.edu/economics/Econ616/Kernel/ast_part1.pdf

³ Walter Zucchini, *Part 1: Kernel Density Estimation*, http://isc.temple.edu/economics/Econ616/Kernel/ast_part1.pdf



**Figure 3: Sample of Longitudes plotted with varying bandwidths
(Appendix lines 38-64)**

You can visualize the kernel density estimate by smoothing a histogram with bins of width $2b$. Imagine that you have a rectangle, with height $\frac{1}{2b}$ and width $2b$, that is placed over each point in the sample on the x-axis. The estimate of $f(x)$ at a given point is $\frac{1}{n}$ times the sum of the heights of all of the rectangles that include that point. This method would be using the rectangular “weighting” function, in which all of points in the rectangle are given an equal weight when calculating the estimate of $f(x)$ at that given point. Figure 4 shows an example of the effect that changing b (denoted bw in the image) has when using a rectangular kernel estimate.

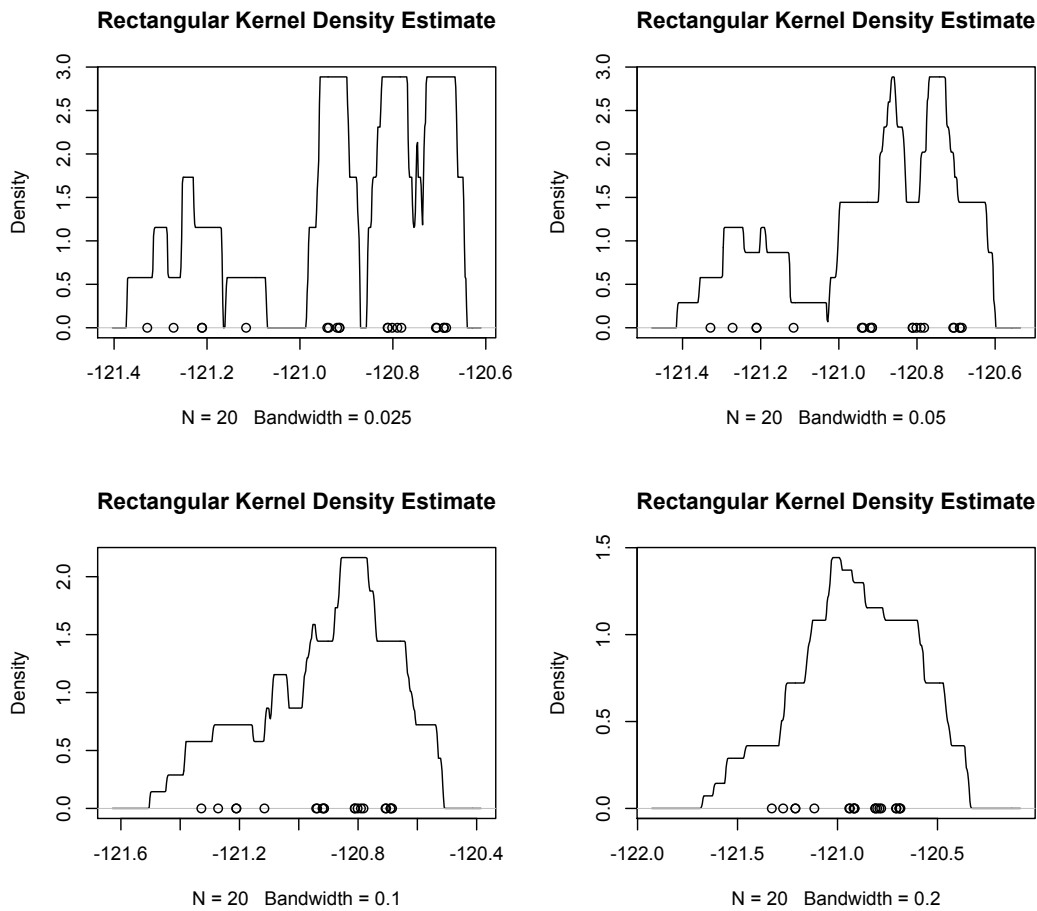


Figure 4: Rectangular Kernel Density Estimates of Sample of Longitudes with varying bandwidths (Appendix lines 69-117)

This series of images (Figure 4) shows the importance of choosing a value for b , which controls the degree of smoothing that is appropriate for the data. You can see that a value of $b=0.025$ results in very scattered peaks that do not do much smoothing of the data at all, whereas a value of $b=0.2$ creates more smoothing in the data, but is slightly too large due to the flat and non-descript nature of the smoothing curve.

In the context of estimating the density of fishing locations (lat/long), we chose an appropriate bandwidth ($b=.0155$) using a cluster analysis of the latitudes and longitudes that were fished to identify clusters that would represent fishing spots. The median size of the fishing spots was used to choose the bandwidth.

As important as it is to choose an appropriate bandwidth for your data, it is also important to consider the type of kernel that you want to use. In the example above the type of kernel is rectangular, while other common types of kernels include triangular, Epanechnikov, and Gaussian. The important idea to note about these kernels is that they are all functions that weight the data and that follow the form,

$$w(t, b) = \frac{1}{h} K\left(\frac{t}{b}\right)$$

where $K\left(\frac{t}{b}\right)$ is a function of the kernel⁴; the kernel density will determine the shape of your smoothing function. For the purposes of our analyses, we applied a Gaussian kernel, which will put more weight on the points in the middle of our kernels and less weight on the points in the tails of the kernel, and will resemble a normal curve.

Because the weights are applied to the points that are encapsulated in each kernel, the effect of a bandwidth that is too small is amplified and the curve will result in having too many peaks. On the other end of the spectrum, a bandwidth that is too large will result in a very shallow and normal-looking curve that does not illustrate any patterns in the data. The data that was modeled using rectangular kernels above is now illustrated using Gaussian kernels, in Figure 5.

⁴ Walter Zucchini, *Part 1: Kernel Density Estimation*,
http://isc.temple.edu/economics/Econ616/Kernel/ast_part1.pdf

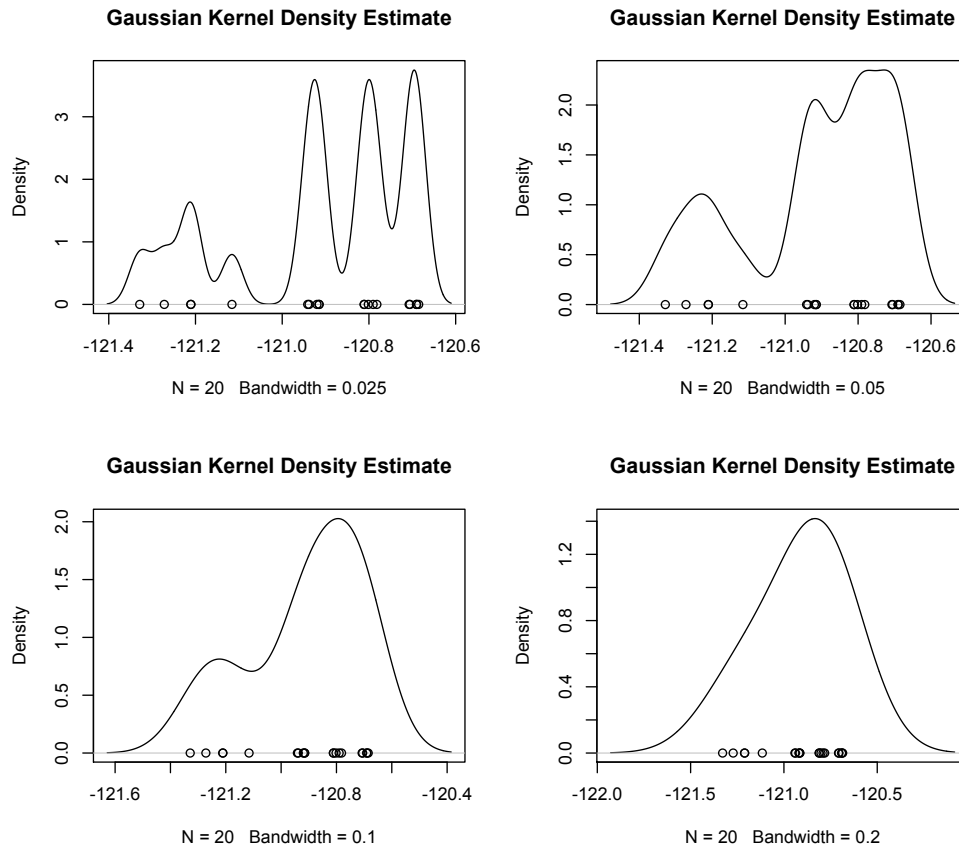


Figure 5: Gaussian Kernel Density Estimation of Sample of Longitudes with varying bandwidths (Appendix lines 122-167)

For the purposes of our data, we use kernel density estimation to obtain a density estimate of the drop locations (latitude and longitude), so we need to generalize the one dimensional kernel density estimation to be multidimensional.

Consider the form of the one-dimensional estimation, where again b is the bandwidth around x_0 , and K is the kernel that controls the weight given to the point x_i based on its proximity to x_0 :

$$\hat{f}(x_0) = \frac{1}{nb} \sum_i K\left(\frac{x_i - x_0}{b}\right).^5$$

This form is the estimation can be generalized to the multidimensional situation, in which different bandwidths are allowed for each direction, where

⁵ Walter Zucchini, *Part 1: Kernel Density Estimation*, http://isc.temple.edu/economics/Econ616/Kernel/ast_part1.pdf

$$\hat{f}(x) = \frac{1}{n} \sum_i \prod_{j=1}^p \frac{1}{b_j} K\left(\frac{x_{ij} - x_{0j}}{b_j}\right).^6$$

We used built-in functions in the software package R to obtain the kernel density estimates of the drop densities. The R code used for these drop location density estimates is located on pages 33 and 34 of the Appendix, from line 461 to line 473.

B. Generalized Additive Model to Smooth Effort Estimations

In order to predict effort values at latitude and longitude values that were not sampled during data collection, we will be using the generalized additive model (gam) function in R. Within the gam function we will be using splines as our smoothing functions to better predict our values for effort. In order to better explain the Generalized Additive Models, or GAM, we will first look at the General Linear Model and the Generalized Linear Model. To begin, consider the task of exploring the association between effort, and latitude and longitude values.

The general linear model, or least squares regression model refers to a situation in which we have a response variable (e.g. effort), that we believe to be some function of other variables (e.g. latitude and longitude). In this standard model, our explanatory variable is assumed to be normally distributed with mean μ and variance σ^2 , where the X's are our predictor variables. These predictor variables are scaled by some coefficient β_i (or b_i in the context of a sample of data) and are summed, giving us the linear predictor that provides the estimated fitted y value according to the given X values. Symbolically, for a sample of data, this relationship looks like the following:

$$y = b_0 + b_1X_1 + b_2X_2.$$

This linear regression model often is too simplified and limited to capture what is really going on with the data, which is why we will next look at a more extended version, which is a generalized linear model.

In exploring this association with the general linear model we are assuming that a function of effort is some linear combination of latitude and longitude. In the generalized linear model, the link function of your variable which relates your predictor variables to a function of your explanatory variable(s), is directly related to the linear combination of your predictors. This link function can also be expressed as the estimated fitted values of your variable, which in the

⁶ Patrick Breheny, *Kernel density estimation*, Slide 22,
<http://web.as.uky.edu/statistics/users/pbreheny/621/F12/notes/10-18.pdf>

context of our example would be the estimated fitted values of effort. The linear combination of the predictor variables refers to, in our case, the values of latitude and longitude that are scaled by some coefficient b_i that is determined by software when the regression is run. This linear relationship can be expressed generally as,

$$g(\mu) = b_0 + b_1X_1 + b_2X_2.$$

One of the biggest differences between the general linear model and the generalized linear model is that distributions other than Gaussian can be applied as the link functions. Thus, the important idea to note here is that the generalized linear model is just an expansion of the standard general linear model that most are familiar with.

Taking the generalized linear model one step further results in the generalized additive model, which is the model that we are using in this analysis. The generalized additive model uses smooth functions of the predictor variables, which can take any number of forms. This model symbolically takes the form of,

$$g(\mu) = b_0 + f(x_1, x_2).$$

The incorporation of the link functions of the linear predictor variables is the key difference between the generalized linear model and the generalized additive model. The addition of the smoothing aspect of this equation allows for more accurate predictions of our effort values, based on a predictive function of latitude and of longitude. We will be using a spline smoother within the GAM function in R, to smooth and predict effort values based on the latitude and longitude.

The idea behind the GAM smoother is extremely similar to that of the kernel density estimators; for every x value, x_0 , we choose a neighborhood around it and fit some type of model, for example a linear regression on the data points captured in that neighborhood. Using the fitted model for the specified neighborhood, you end up with a fitted value corresponding to that specific x_0 , and if we repeat this process for every x_0 in our sample we would end up with fitted values based on a rolling neighborhood that is relative to each x value.⁷ Instead of fitting a linear regression, we can fit a polynomial regression or some other type of model that gives weight to the x values in a given neighborhood based off of their relative distances from x_0 . In the context of our analysis, the function we will use to weight our values is a spline smoother. Within these spline smoothers there are two categories, natural splines and b-splines; R uses b-splines for its estimations, so that is the function that will be the basis of our resulting analyses.

⁷ Michael Clark, *Generalized Additive Models*, Center for Social Research University of Notre Dame, Page 7, <http://www3.nd.edu/~mclark19/learn/GAMS.pdf>

Splines are more complex smoothing functions because a spline curve is actually a piecewise polynomial curve that joins together two or more curves, or “basis functions”, at locations called “knots”. A spline is defined as being a piecewise $m-1$ degree polynomial that is continuous up to its first $m-2$ derivatives; the continuity requirements allows for the curve to be as smooth as possible. On the following page, Figure 6 shows an example of two curves joined at a knot at $x=10$. This example is for illustrative purposes only, because this piecewise curve is not continuously differentiable, and this cannot be a true spline. More flexible curves can be obtained by increasing the degree of the spline and/or by increasing the number of knots.⁸

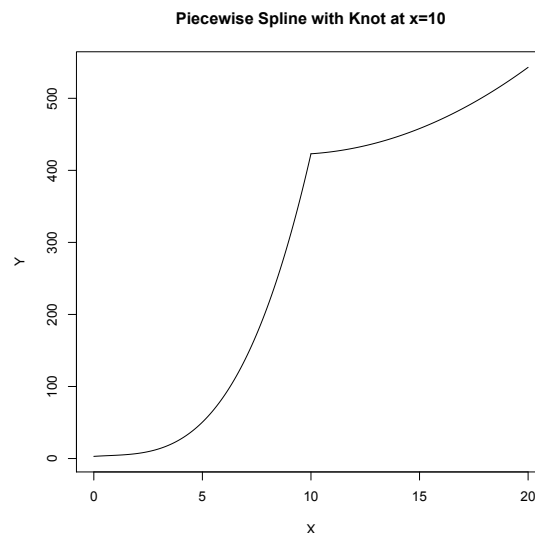


Figure 6: Piecewise Curve with a “Knot”
(Appendix lines 178-188)

However, as with the kernel density estimation, there are tradeoffs for increasing or decreasing the number of knots used: having too few knots results in the functions being too restrictive and not fitting the data well while having too many knots leads to the risk of over fitting your data.

As with any estimation, it is important to also consider the error of these estimations, and is always helpful to construct confidence intervals illustrating the accuracy of your predictions. As stated previously, we will be working with the highly complicated but more stable and efficient spline in our R work and analyses, including the example the follows.

To illustrate the workings of spline smoothing functions, we will look at a simplified example of what we are doing, by looking at predicting effort from just a single predictor, longitude. The equation that goes along with the single predictor equation is

$$\hat{y} = f(x),$$

⁸ Patrick Breheny, *Kernel density estimation*,
<http://web.as.uky.edu/statistics/users/pbreheny/621/F12/notes/10-18.pdf>

where f is a smooth function, specifically a smooth function of longitude for the following example.

The following images and analyses were based on the same sample of 20 longitudes, and their corresponding 20 efforts values. Figure 7 shows a scatterplot of the sample of twenty longitudes and their corresponding efforts that are being used for this example.

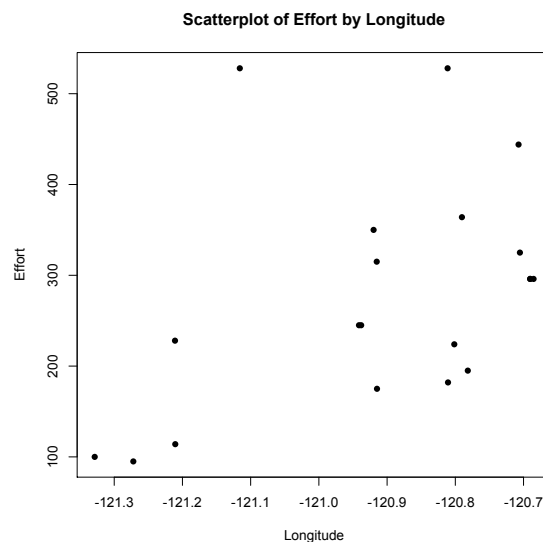
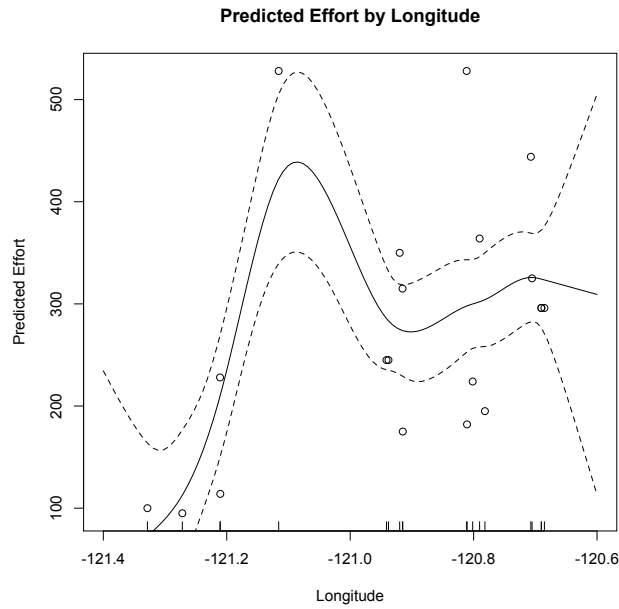


Figure 7: Scatterplot of Sample of Longitudes with Corresponding Effort Values (Appendix lines 192-211)

In Figure 8, the 20 sample longitude points are plotted against their relative predicted efforts (calculated with the spline function in R), as well as the spline curve that predicts the effort at all points between -121.4 and -120.6. Because these are predicted, or estimated, effort values it is important to show what the variability is around your estimations. The variability in the estimations is represented in this plot as the dotted lines that fall on either side of the prediction curve. These lines are the 95% confidence interval lines for the predictions, and you can see that the confidence lines show the most variability (are the farthest away from the line) in the places where there are little or no recorded effort values to base the predictions off of. Good illustrations of this occur at longitude values of about -121.2 and also around -120.6. On this graph there are also tick marks along the longitude axis that represent where the sample data points fall, and we can again look at the space where there are little or no tick marks and see that at those values the variability around the estimates is much higher.



**Figure 8: Spline Curve to Predict Effort from Longitude
with 95% Confidence Bands
(Appendix lines 216-225)**

For our actual analyses, we will be carrying out the same basic process, however we will be predicting effort using an interactive spline model that includes a spline smoother that will be incorporating both longitude and latitude values, and the interaction between the two variables. This model is represented by,

$$\hat{y} = f(x_1, x_2),$$

where x_1 is the latitude and x_2 is the longitude. This model will allow us to predict where and how often effort is being exerted while fishing for the Central Coast of California, both where we do and do not have existing data.

As previously mentioned, it is extremely important to be able to include how much error is associated with your predictions. In order to predict this error, we will use a two-stage model with bootstrapping.

C. Two-Stage Bootstrapping to Estimate Fishing Effort and Variability of Estimates

The purpose of using bootstrapping is primarily to estimate the variability or uncertainty in the effort predictions. The bootstrap process is shown in Figure 9 and is described as follows. First, start with the original sample of data, of size

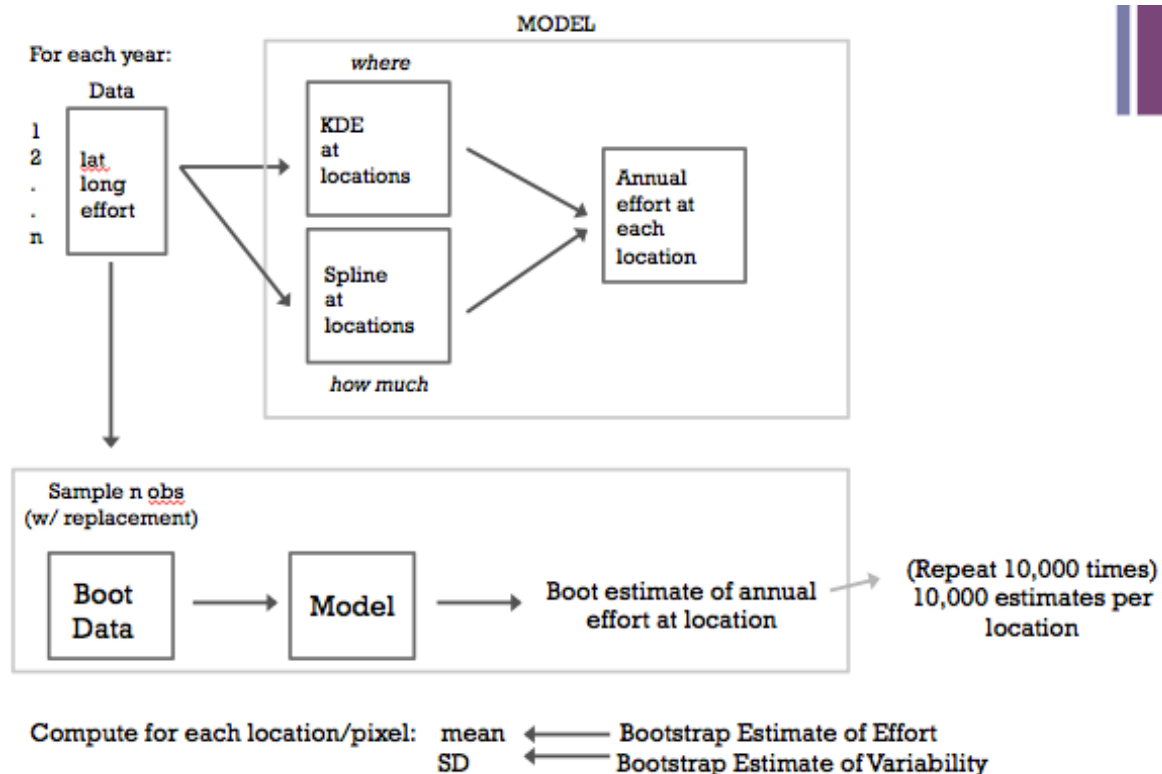
n. Then, sample n observations from the original data, with replacement, and call this the “boot data”. The original sample size and thus the size of the boot data will change depending on the year that the analysis is being performed on. This boot data is now fit using the two-stage model as previously explained- KDE and splines. The KDE allows us to determine where the fisherman are fishing, the spline allows us to determine how often the fisherman are fishing in certain location, and together they allow us to determine the bootstrap estimate of annual effort at each location on our map. This annual estimate is calculated by

$$total \# \text{ drops} * prob \text{ of drop (at each location)} * effort \text{ (at each location)}.$$

In this equation, the probability of a drop at each location, or pixel, is determined by the KDE and the effort at each location/pixel, is determined by the spline.

We will repeat this process 5,000 times, which will result in 5,000 estimates for annual effort at each location. To be able to create a single graph depicting the bootstrapped effort estimates and variability estimates, the final step is to take these 5,000 estimates and take the mean, which will result in the bootstrap estimate of effort, and take the standard deviation, which will result in the bootstrap estimate of variability.

Figure 9: Map of Bootstrap Process with a Two-Stage Model

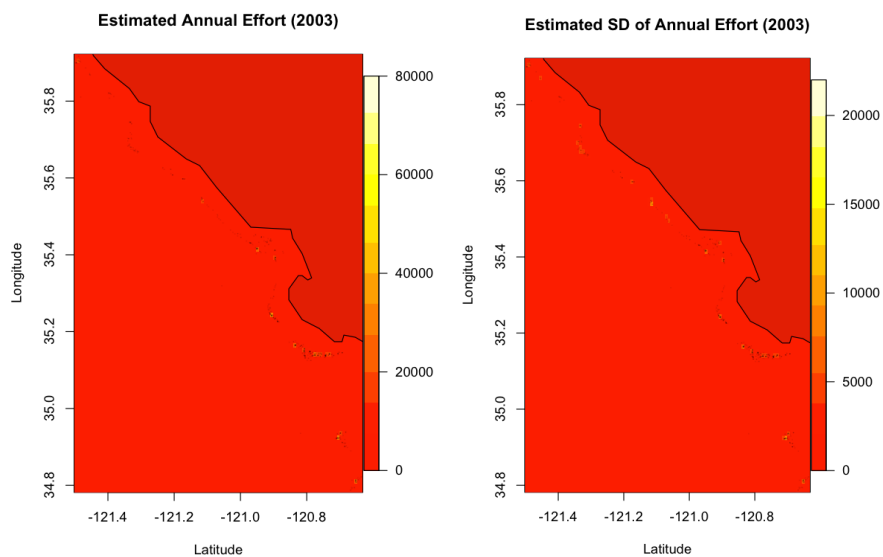


IV. Results

A. Estimation of Effort (KDE and Splines)

Using the bootstrapping as well as a combination of the kernel density estimation to estimate where fisherman were fishing, and splines to estimate how much effort was being put in at each location, the resulting images give a good picture of the fishing patterns along the central coast, from year to year. Figure 10 shows an example of the images that will be looked at in the following sections; these two images show the estimated effort and estimated variability in effort for the year 2003.

Figure 10: 2003 Estimated Annual Effort and Estimated Variability



For all 9 years of data, an image of the estimated annual effort has been created with the estimated effort at each pixel being measured on a heat scale from 0 to 80,000. In Figure 11 below, the estimated annual effort for 2003 for the whole Central Coast is placed next to a zoomed-in portion of the coast. This smaller portion of the Central Coast allows us to better see how these estimation are mapped and how the effort in this section is distributed; the enhanced image is also on a smaller heat scale (0 to 30,000) to better see how much effort is estimated at each pixel.

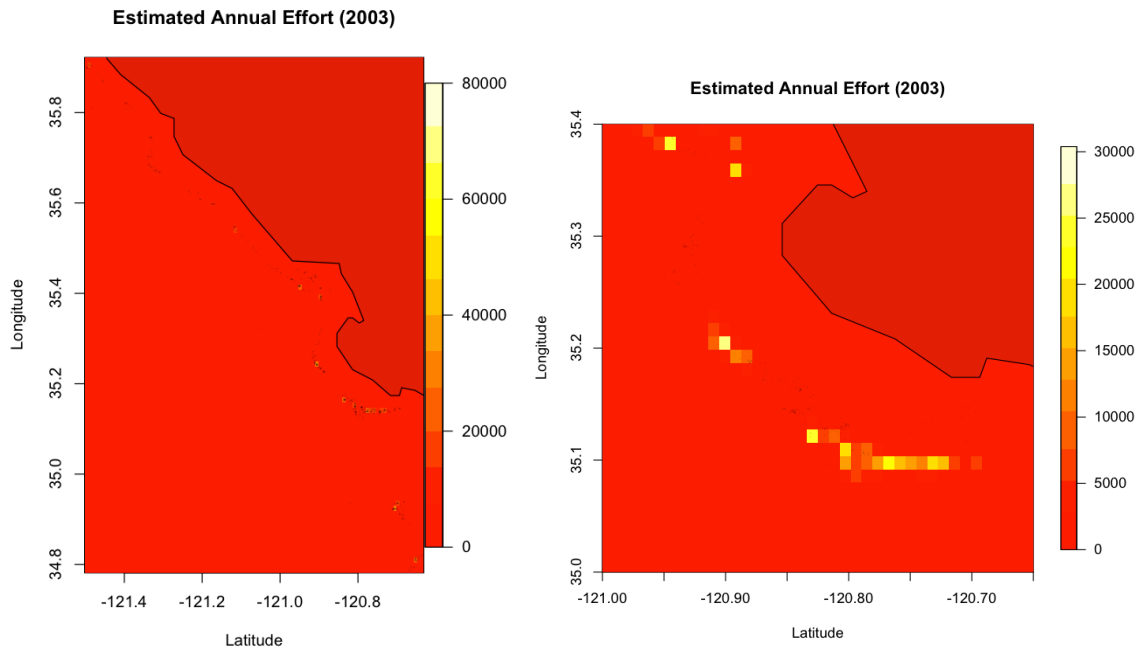


Figure 11: 2003 Estimated Annual Effort with Enhanced Portion to Illustrate Pixel-Wise Estimation of Effort (Appendix lines 566-576, 596-604)

To investigate whether or not the fishing patterns have changed since the mpa's were put in to place, we can compare the images in Figure 12, which depict the fishing patterns for the pre-mpa years, to the images in Figure 13, which depict the fishing patterns for the post-mpa years.

Figure 12: Pre MPA (2003-2006) Estimated Annual Effort
(Appendix lines 568-576 repeated for each year)

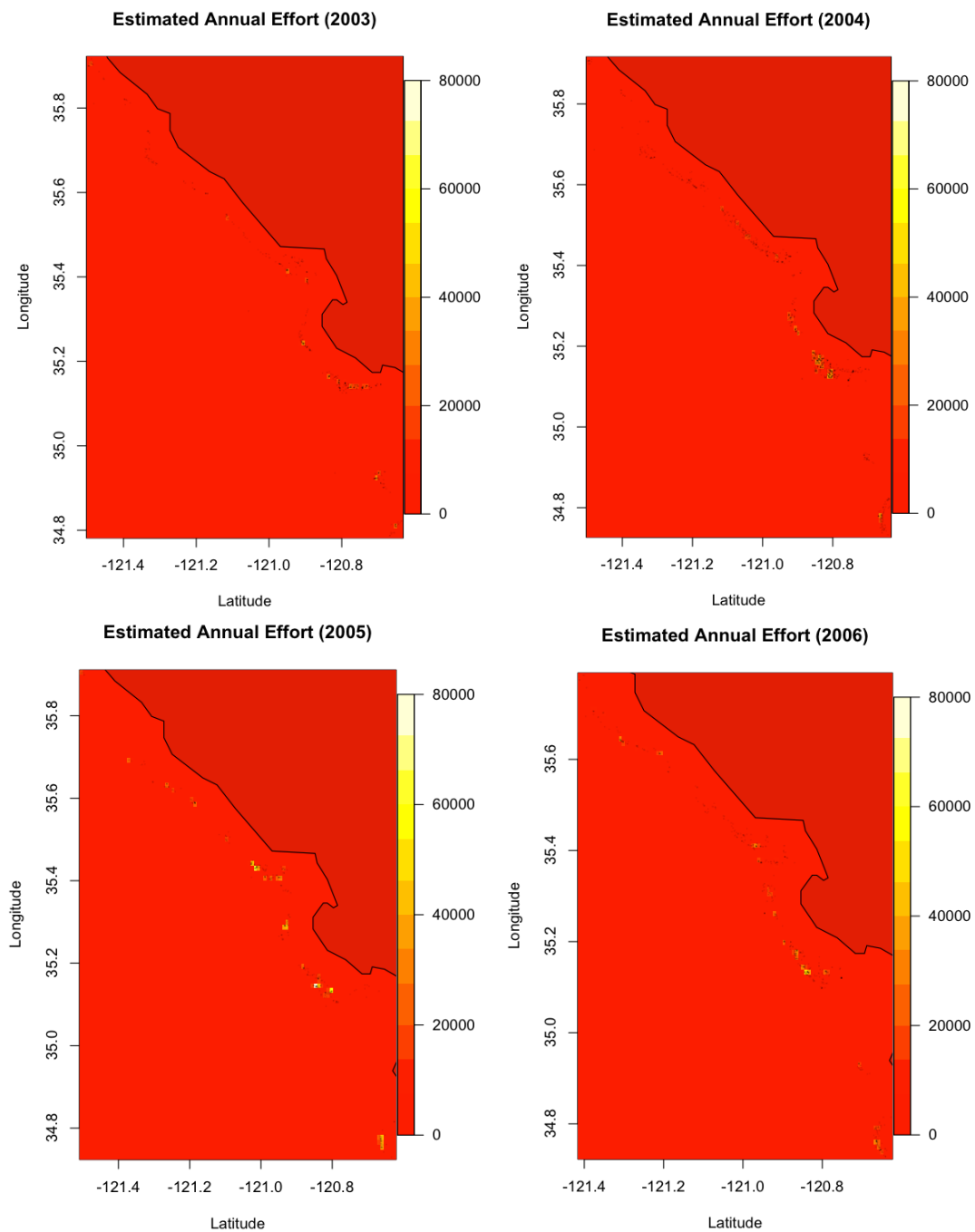
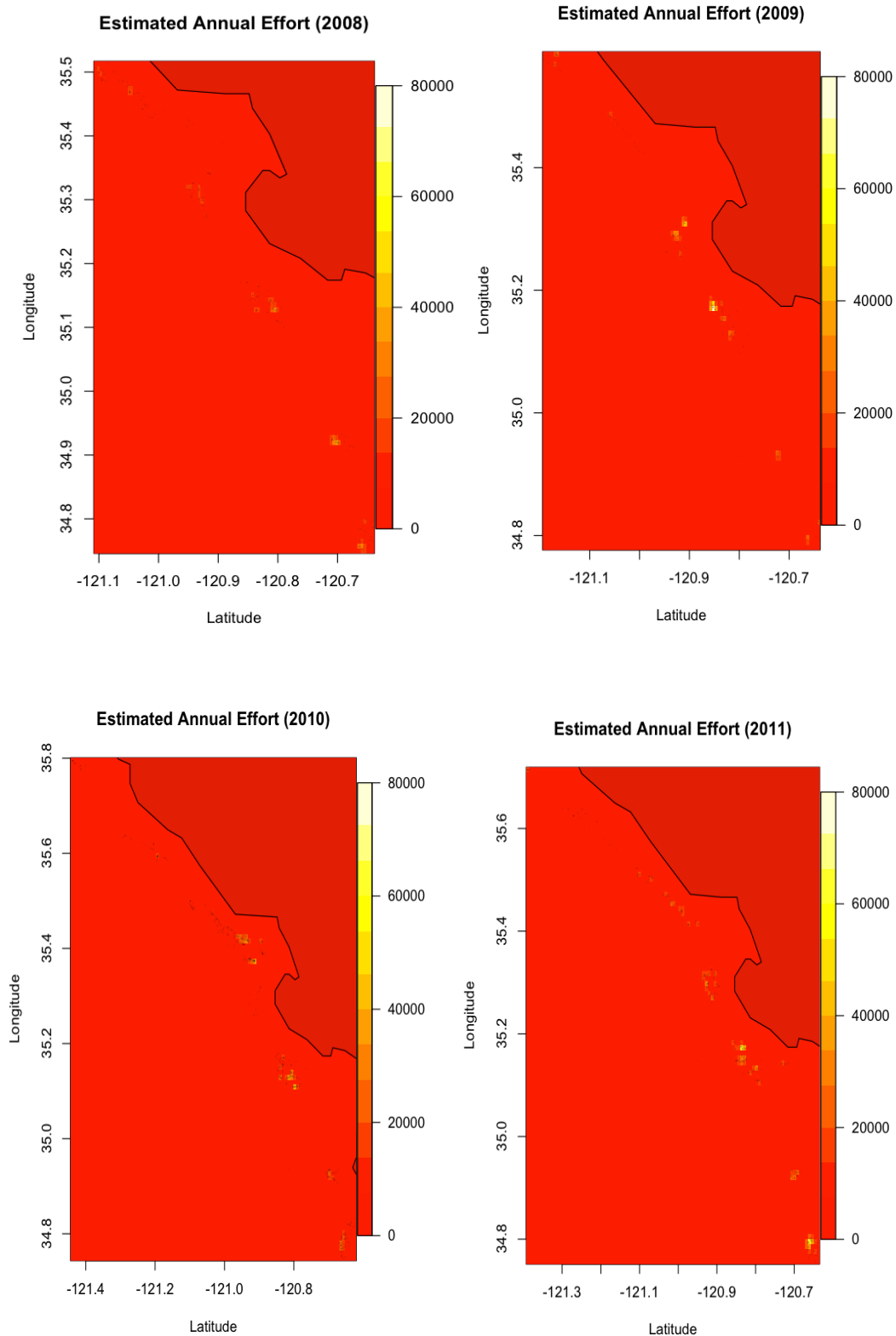
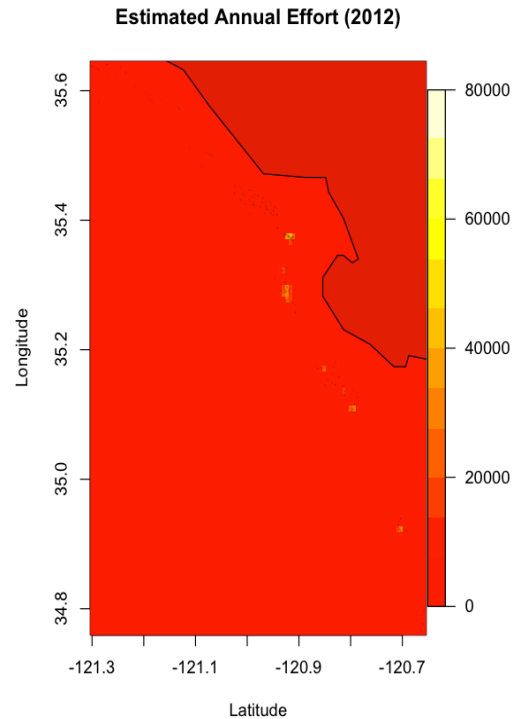


Figure 13: Post MPA (2008-2012) Estimated Annual Effort,
Continues on page 20
(Appendix lines 568-576 repeated for each year)





From looking at the nine images of annual effort, it is not perfectly clear whether or not the pattern of effort changed substantially after the marine protected areas were put in place. However, there are interesting patterns to note such as the effort generally getting larger from 2003 to 2005, which we can see based on the pixels becoming brighter. Also, in the post-mpa years the fishing effort is more condensed into specific locations, rather than being spread along the coast which could potentially be attributed to the areas where fishing was no longer allowed.

B. Estimation of Variability (Bootstrapping)

Bootstrapping our data through the two-stage model of KDE and Splines allows for the estimation of the variability that surrounds the effort estimations at each location; the estimate of this variability for each year is shown based on a heat scale ranging from 0 to 22,000. In Figure 14, the estimated variability in our data for 2003 is shown next to a zoomed in portion of the Central Coast (the same portion that was provided in Figure 11). By looking at the selected portion of the coast in Figure 14, we can see that the variability around these estimates is moderately high; the fairly high standard deviations could be attributed to the small amount of data that we have, and that we are using to try to predict effort along the whole Central Coast.

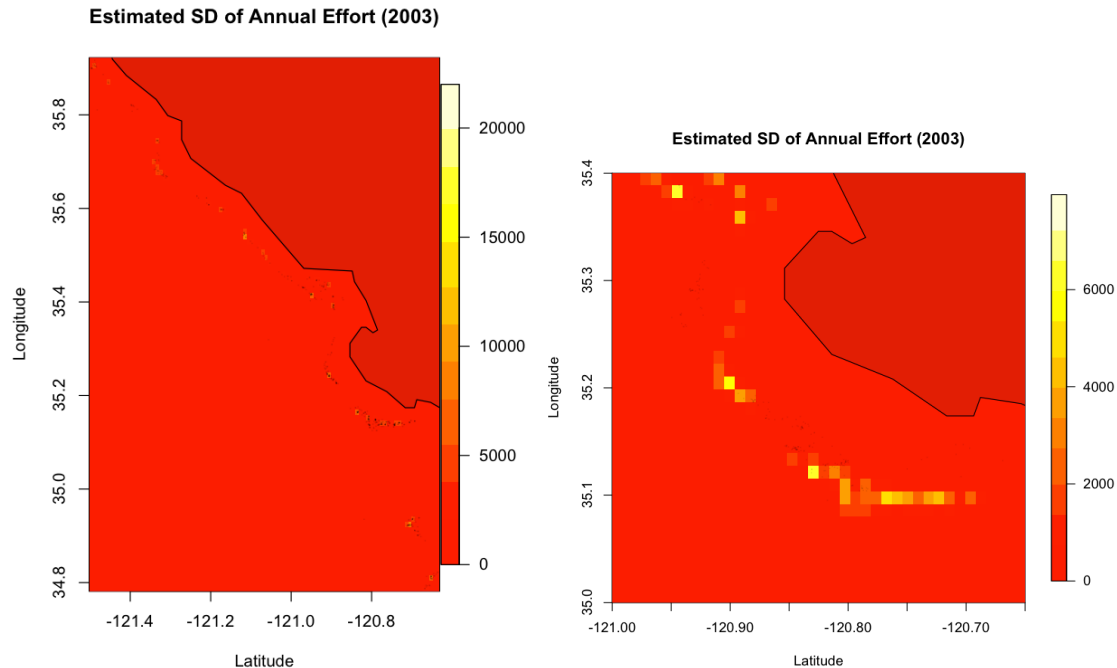


Figure 14: 2003 Estimated Annual Effort with Enhanced Portion to Illustrate Pixel-Wise Estimation of Effort (Appendix lines 579-587, 607-615)

In addition to looking at the patterns in estimated effort from year to year, looking at the estimated variability from year to year can tell us a lot about our data; to do this we will look at Figures 15 and 16 on the following pages. The years with the brightest pixels represent the years with the highest variability, and the ones that stand out are the years 2005 and 2009. These are also the years that were found to have higher estimated annual efforts. The trend appears to follow that the higher the estimated annual effort is, the higher the estimated variability will be also; this is an interesting observation to note because this is telling us that we can generally be less certain about the accuracy of our estimations when we are estimating higher values of effort. There does not appear to be any significant differences in the variability between the pre-mpa years and the post-mpa years, because the variability varies greatly within the pre-mpa and post-mpa groups individually.

**Figure 15: 2003 Estimated Standard Deviation of Annual Effort
with Enhanced Portion to Illustrate Pixel-Wise Estimation of Effort
(Appendix lines 579-587 repeated for each year)**

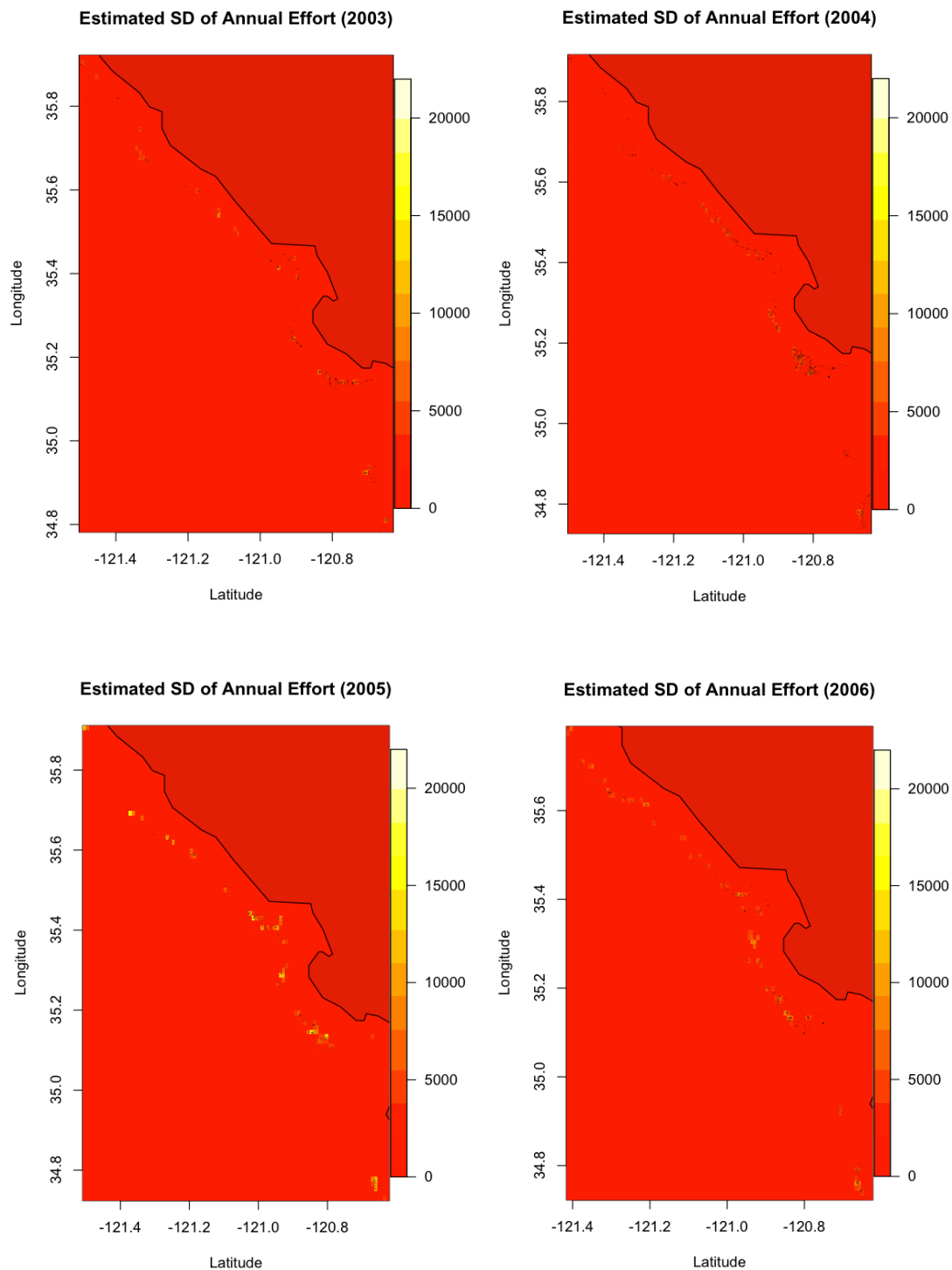
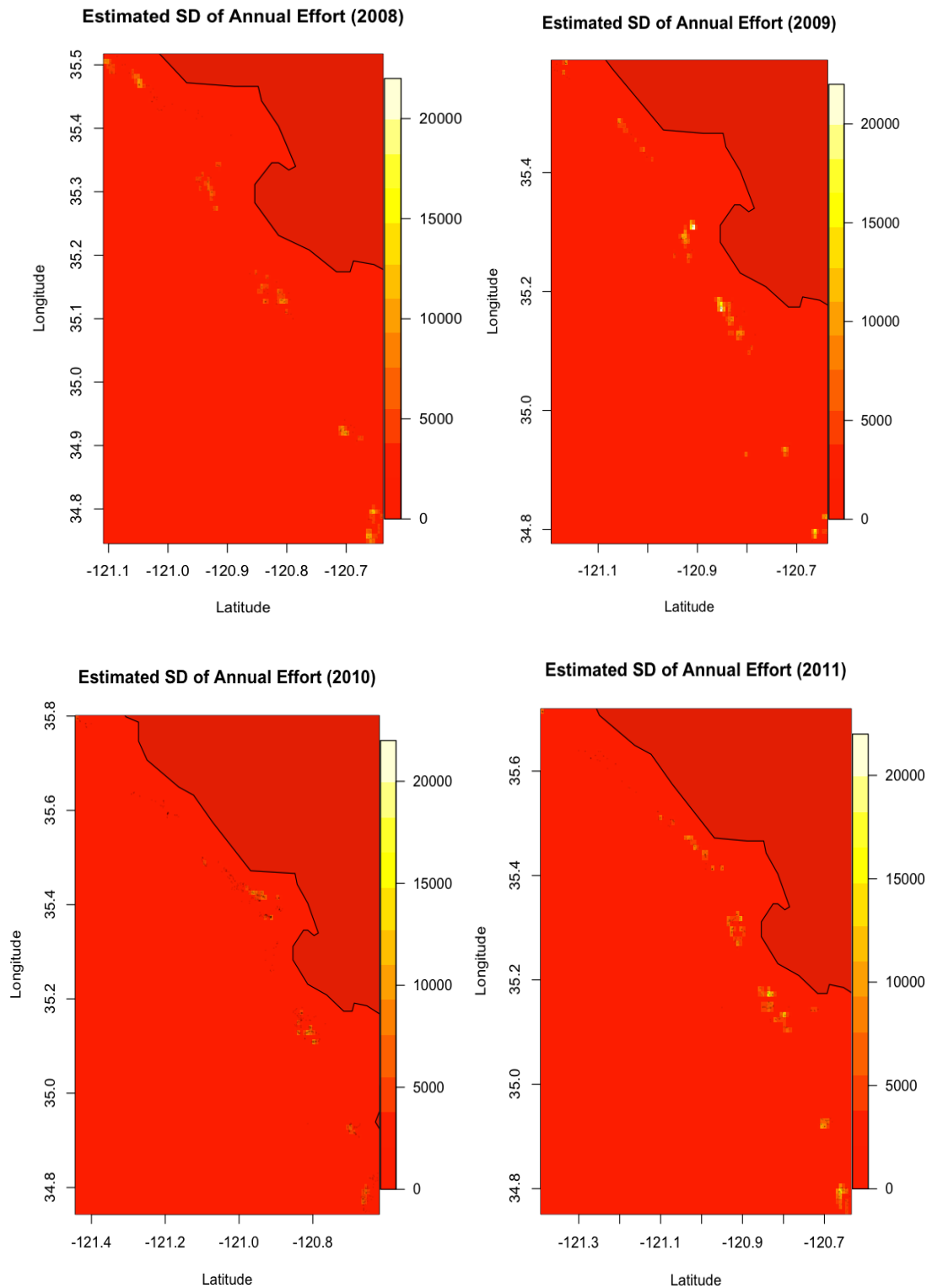
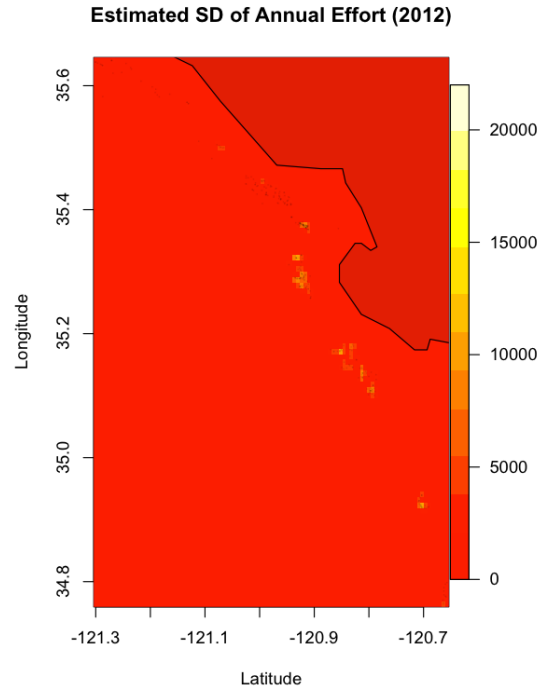


Figure 16: Post MPA (2008-2012) Estimated Standard Deviation of Annual Effort, Continues on page 24
(Appendix lines 579-587 repeated for each year)





C. Annual Effort Pre and Post MPA

One of the driving forces for this project was the question of whether or not fishing effort has changed due to the implementation of the marine protected areas along the Central Coast. Another way to investigate this question is to look at the difference in average annual effort for the pre-mpa years and the post-mpa years. To do this we will compute a 95% confidence interval for the difference in average annual effort before and after the mpa implementation, using the following values:

t_i = total annual effort averaged over all locations, for $i=2003-6, 2008-12$

$$\hat{d} = -\frac{t_{2003}+t_{2004}+t_{2005}+t_{2006}}{4} + \frac{t_{2008}+t_{2009}+t_{2010}+t_{2011}+t_{2012}}{5}, \text{ the}$$

difference in average annual effort pre and post mpa

$\hat{S}_{ti}^2 = (\text{standard deviation of } t_i)^2$, the variance of the bootstrapped annual effort

$$\hat{S}_d^2 = \left(\frac{\hat{S}_{t2003} + \hat{S}_{t2004} + \hat{S}_{t2005} + \hat{S}_{t2006}}{4} + \frac{\hat{S}_{t2008} + \hat{S}_{t2009} + \hat{S}_{t2010} + \hat{S}_{t2011} + \hat{S}_{t2012}}{5} \right)^2$$

the variance of the average difference in annual effort pre and post mpa.

Finally, our 95% confidence interval will take the following form:

$$\hat{d} \pm 1.96 * \hat{S}_d.$$

Using the code provided in the Appendix, from lines 621 to 670, the resulting values are $\hat{d} = 188080.2$, and $\hat{S}_d = 45254.87$. Using these numbers to plug in to the equation above, the resulting confidence interval is:

$$188080.2 \pm 1.96 * 45254.87 = (99380.68, 276779.8).$$

Based on this interval, we are 95% confidence that the average bootstrapped estimated annual effort after the mpa's were put in place is between 99380.68 and 276779.8 higher than the average bootstrapped estimated annual effort before the mpa's were implemented. This information tells us that, regardless of where the fishermen are fishing, they have been fishing more since the mpa's were implemented. The scope of our project does not allow us to determine why this is the case, however it could be speculated that this could be due to there being less fish outside of the mpa's, which causes the fisherman to have to fish for longer (put in more effort) in order for everyone to catch the desired number of fish.

D. Limitations

The major limitations that we came across during this project were the small proportion of total trips per year that we had data on, and the inability to calculate the average difference in annual fishing effort pre and post mpa, per pixel. The small amount of data did not pose an issue, other than the fact that it caused our estimated effort for each location to be less accurate/have more variability than desired. The larger problem we had was when trying to calculate the difference in average effort between the two groups of years.

When writing the code, we did not yet know that we would have enough time to be able to look at the difference between the groups of years, so the code was not written to be compatible with that procedure. In order to compute the difference pixel-wise, we would have had to specify a set range for latitudes and longitudes to be used within the bootstrap, which would ensure that the limits of all 9 years would match-up. Since we did not include this specified range, the latitude and longitude limits on the 9 years are non consistent, which keeps us from being able to compute the pixel by pixel difference in average annual effort.

V. Appendix

A. R Code

```

1
2 #####
3 #
4 # KDE   examples
5 #
6 #####
7
8
9 # load required packages
10 library(maps)
11 library(MASS)
12 library(mgcv)
13 library(fields)
14 library(akima)
15
16
17 # sample of latitudes and longitudes n=20 and efforts
18 lat = c(35.125, 34.91, 35.13667, 35.14867, 35.545, 34.93462,
19         34.92433, 34.91, 34.91933, 35.42633, 35.427, 35.40567, 35.4315,
20         35.4085, 35.1231, 35.12617, 35.6127, 35.61125, 35.63847,
21         35.6975)
22
23 long = c(-120.8113, -120.6903, -120.7817, -120.7903, -121.1159, -
24          120.7073, -120.7053, -120.6903, -120.6853, -120.9152, -120.9148,
25          -120.938, -120.9198, -120.9412, -120.8107, -120.8015, -121.2105,
26          -121.2109, -121.272, -121.3286)
27
28 effort = c(528, 296, 195, 364, 528, 444, 325, 296, 296, 315, 175,
29            245, 350, 245, 182, 224, 114, 228, 95, 100)
30 #fishing hours, total hours all lines combined
31
32
33
34 ### Examples of Kernel Density Estimation to Estimate Drop
35 Densities
36
37
38 ##EXAMPLE 1: Differences between bandwidths
39
40 #create 2x2 grid for images
41 par(mfrow=c(2,2))
42
43 #examples with different bandwidths and one smooth line
44 #bin width = .4
45 hist(long, prob=TRUE, main="Histogram of Longitudes (bandwidth=
46      .4)", xlab="Longitude (n=20)", ylab="Density", breaks=seq(-

```

```

47 121.4,-120.6, by=.4), ylim=c(0,2.5))
48
49
50 #bin width = .1
51 hist(long, prob=TRUE, main="Histogram of Longitudes (bandwidth=
52 .1)", xlab="Longitude (n=20)", ylab="Density", breaks=seq(-
53 121.4,-120.6, by=.1), ylim=c(0,2.5))
54
55
56 #bin width = .025
57 hist(long, prob=TRUE, main="Histogram of Longitudes (bandwidth=
58 .05)", xlab="Longitude (n=20)", ylab="Density", breaks=seq(-
59 121.4,-120.6, by=.05), ylim=c(0,5))
60
61
62 #Example of kernel density estimate
63 k1= density(long, bw=.1)
64 plot(k1,type="l",main="Kernel Density Estimate")
65
66
67
68
69 ##EXAMPLE 2: Differences between bandwidths with rectangular
70 kernels
71
72 #create 2x2 grid for images
73 par(mfrow=c(2,2))
74
75 #rectangular with bw=.025
76 k2a= density(long, bw=.025, kernel="rectangular")
77 plot(k2a,type="l",main="Rectangular Kernel Density Estimate")
78 points(long, rep(0, length(long)))
79
80 #hist(long, prob=TRUE, main="Rectangular Kernel (bw=.025)",
81 xlab="Longitude (n=20)", ylab="Density", ylim=c(0,3),
82 border="grey")
83 #lines(k2a, lwd=2)
84
85
86 #rectangular with bw=.05
87 k2b= density(long, bw=.05, kernel="rectangular")
88 plot(k2b,main="Rectangular Kernel Density Estimate")
89 points(long, rep(0, length(long)))
90
91 #hist(long, prob=TRUE, main="Rectangular Kernel (bw=.05)",
92 xlab="Longitude (n=20)", ylab="Density", ylim=c(0,3),
93 border="grey")
94 #lines(k2b)
95 #plot(k2b,type="l",main="Kernel Density Estimate")
96
97
98 #rectangular with bw=.1

```

```

99  k2c= density(long, bw=.1, kernel="rectangular")
100 plot(k2c, main="Rectangular Kernel Density Estimate")
101 points(long, rep(0, length(long)))
102
103 #hist(long, prob=TRUE, main="Rectangular Kernel (bw=.1)",
104       xlab="Longitude (n=20)", ylab="Density", ylim=c(0,3),
105       border="grey")
106 #lines(k2c)
107
108
109 #rectangular with bw=.2
110 k2d= density(long, bw=.2, kernel="rectangular")
111 plot(k2d, main="Rectangular Kernel Density Estimate")
112 points(long, rep(0, length(long)))
113
114 #hist(long, prob=TRUE, main="Rectangular Kernel (bw=.2)",
115       xlab="Longitude (n=20)", ylab="Density", ylim=c(0,3),
116       border="grey")
117 #lines(k2d)
118
119
120
121
122 ##EXAMPLE 3: Differences in between bandwidths with Gaussian
123 kernels
124
125 #create 2x2 grid for images
126 par(mfrow=c(2,2))
127
128
129 #gaussian with bw=.025
130 k3a= density(long, bw=.025, kernel="gaussian")
131 plot(k3a, main="Gaussian Kernel Density Estimate")
132 points(long, rep(0, length(long)))
133
134 #hist(long, prob=TRUE, main="Gaussian Kernel (bw=.025)",
135       xlab="Longitude (n=20)", ylab="Density", ylim=c(0,3.6))
136 #lines(k3a)
137
138
139 #gaussian with bw=.05
140 k3b= density(long, bw=.05, kernel="gaussian")
141 plot(k3b, main="Gaussian Kernel Density Estimate")
142 points(long, rep(0, length(long)))
143
144 #hist(long, prob=TRUE, main="Gaussian Kernel (bw=.05)",
145       xlab="Longitude (n=20)", ylab="Density", ylim=c(0,3.6))
146 #lines(k3b)
147
148
149 #gaussian with bw=.1
150 k3c= density(long, bw=.1, kernel="gaussian")

```

```

151 plot(k3c, main="Gaussian Kernel Density Estimate")
152 points(long, rep(0, length(long)))
153
154 #hist(long, prob=TRUE, main="Gaussian Kernel (bw=.1)",
155       xlab="Longitude (n=20)", ylab="Density", ylim=c(0,3.6))
156 #lines(k3c)
157
158
159 #gaussian with bw=.2
160 k3d= density(long, bw=.2, kernel="gaussian")
161 plot(k3d, main="Gaussian Kernel Density Estimate")
162 points(long, rep(0, length(long)))
163
164 #hist(long, prob=TRUE, main="Gaussian Kernel (bw=.2)",
165       xlab="Longitude (n=20)", ylab="Density", ylim=c(0,3.6),
166       border="light grey", col="grey")
167 #lines(3d)
168
169
170
171
172 #####
173 #                                     #
174 # Spline examples                     #
175 #                                     #
176 #####
177
178 ### Examples for spline estimation of effort
179
180 #Graph #1: generic example of knots in spline
181 x1=seq(0,10,length=100)
182 x2=seq(10,20,length=100)
183 y1=3 + 2*x1 - x1^2 + .5*x1^3
184 y2=423 + 2*x1 + x1^2
185
186
187 plot(c(x1,x2), c(y1,y2), xlab="X", ylab="Y", main="Piecewise Spline
188       with Knot at x=10", type="l")
189
190
191
192 #sample of latitudes and longitudes n=20 and efforts
193
194 lat = c(35.125, 34.91, 35.13667, 35.14867, 35.545, 34.93462,
195        34.92433, 34.91, 34.91933, 35.42633, 35.427, 35.40567, 35.4315,
196        35.4085, 35.1231, 35.12617, 35.6127, 35.61125, 35.63847, 35.6975)
197
198 long = c(-120.8113, -120.6903, -120.7817, -120.7903, -121.1159, -
199         120.7073, -120.7053, -120.6903, -120.6853, -120.9152, -120.9148, -
200         120.938, -120.9198, -120.9412, -120.8107, -120.8015, -121.2105, -
201         121.2109, -121.272, -121.3286)
202
203 effort = c(528, 296, 195, 364, 528, 444, 325, 296, 296, 315, 175,

```



```

258 #load required packages
259 library(maps)
260 library(MASS)
261 library(mgcv)
262 library(fields)
263 library(akima)
264
265 #Read in data
266 #setwd("/Volumes/USB/Senior Project")
267 #setwd("F:/Senior Project")
268 setwd("/Users/samdellinger/Documents/Cal Poly 2013-14/Senior
269 Project")
270 fishing.data<- read.table('FishingFullDataSet.csv', header= T,
271 sep=",")
272
273 ##Run through all of analyses individually for each year
274
275 # subset data into years; run invididually
276 #remove outlier in 2005 subset of data
277 fishing.data = subset(fishing.data, subset = Year == 2003)
278 #fishing.data = subset(fishing.data, subset = Year == 2004)
279 #fishing.data = subset(fishing.data, subset = Year == 2005&LongDD>=
280 250)
281 #fishing.data = subset(fishing.data, subset = Year == 2006)
282 #fishing.data = subset(fishing.data, subset = Year == 2008)
283 #fishing.data = subset(fishing.data, subset = Year == 2009)
284 #fishing.data = subset(fishing.data, subset = Year == 2010)
285 #fishing.data = subset(fishing.data, subset = Year == 2011)
286 #fishing.data = subset(fishing.data, subset = Year == 2012)
287
288
289 #Plot data with scatterplot
290 plot(fishing.data$LongDD, fishing.data$LatDD, main='Scatterplot of
291 Lat vs. Long', xlab='LatDD', ylab='LongDD')
292
293
294 #Useful base map for properly scaled plots
295 # run this map without any graphics windows first, then
296 # all subsequent graphics will be have aspect ratios
297 # that are scaled properly
298
299
300 # Ran alone creates simple image of CA coastlines
301 map(database = "state", regions = "CA", xlim =
302 range(fishing.data$LongDD)+c(-.1,.1), ylim =
303 range(fishing.data$LatDD)+c(-.1, .1), fill = TRUE, col =
304 'darkgreen')
305 # add drops to above plot
306 points(fishing.data$LongDD, fishing.data$LatDD, pch = 16, col =
307 rgb(0,0,0,.1), cex = .2)
308
309
310 # Store map info
311 map.info = map(database = "state", regions = "CA", xlim =

```

```

312   range(fishing.data$LongDD)+c(-.1,.1), ylim =
313   range(fishing.data$LatDD)+c(-.1, .1), fill = TRUE, col =
314   'darkgreen')
315 map.plot = cbind(x = map.info$x, y = map.info$y)
316
317 # Plot of effort with circles proportional to effort
318 map(database = "state", regions = "CA", xlim =
319   range(fishing.data$LongDD)+c(-.1,.1), ylim =
320   range(fishing.data$LatDD)+c(-.1, .1), fill = TRUE, col =
321   'darkgreen')
322 symbols(fishing.data$LongDD, fishing.data$LatDD, circles =
323   fishing.data$Effort, fg = rgb(0,0,0,.05), inches = .5, add = TRUE)
324
325
326
327
328 #####
329 #                                     #
330 #      KDE to estimate drop denisty      #
331 #                                     #
332 #####
333
334 #bandwidth previously determined using clutser analysis; median
335   fishing spot size
336
337 kde = with(fishing.data, kde2d(LongDD, LatDD, n=100, h=.0155))
338 image.plot(kde, col = heat.colors(50))
339 map(database = "state", regions = "CA", xlim =
340   range(fishing.data$LongDD)+c(-.1,.1), ylim =
341   range(fishing.data$LatDD)+c(-.1, .1), fill = TRUE, col =
342   'darkgreen', add = TRUE)
343 points(fishing.data$LongDD, fishing.data$LatDD, pch = 16, col =
344   rgb(0,0,0,.1), cex = .2)
345
346 #change years
347 title("KDE (2003)")
348
349 #total drops
350 #different number of trips per year
351
352 N = 2731 #2003
353 #N = 3580 #2004
354 #N = 2313 #2005
355 #N = 3556 #2006
356 #N = 4114 #2008
357 #N = 4188 #2009
358 #N = 3790 #2010
359 #N = 4239 #2011
360 #N = 3787 #2012
361
362 pixel.ar = diff(kde$x[1:2]) * diff(kde$y[1:2])
363 tot.est.drops = N * kde$z/sum(kde$z * pixel.ar) * pixel.ar
364 image.plot(kde$x, kde$y, tot.est.drops, col = heat.colors(50), xlim
365   = range(fishing.data$LongDD)+c(-.1,.1), ylim =

```

```

366   range(fishing.data$LatDD)+c(-.1, .1))
367 map(database = "state", regions = "CA", fill = TRUE, col =
368   'darkgreen', add = TRUE)
369 points(fishing.data$LongDD, fishing.data$LatDD, pch = 16, col =
370   rgb(0,0,0,.1), cex = .2)
371 title("Total Estimated number of Drops in pixel")
372 sum(tot.est.drops)
373 # evidence of some bias, so divide kde$z by sum(kde$z) in calcs
374
375
376
377
378 #####
379 #                                     #
380 #Spline (within GAM) to estimate effort#
381 #                                     #
382 #####
383
384 gam.fit = gam(Effort ~ s(LongDD, LatDD), data = fishing.data)
385 summary(gam.fit)
386 vis.gam(gam.fit, plot.type = "contour", main = NULL)
387 map(database = "state", regions = "CA", xlim =
388   range(fishing.data$LongDD)+c(-.1,.1), ylim =
389   range(fishing.data$LatDD)+c(-.1, .1), fill = TRUE, col =
390   rgb(0,100/256,0,.1), add = TRUE)
391 symbols(fishing.data$LongDD, fishing.data$LatDD, circles =
392   fishing.data$Effort, fg = rgb(0,0,0,.05), inches = .5, add = TRUE)
393 title("Effort")
394
395
396 #predicted values
397 pred.vals = data.frame(expand.grid(LongDD = kde$x, LatDD = kde$y))
398 effort.pred = matrix(predict(gam.fit, pred.vals), ncol = 100)
399 image.plot(kde$x, kde$y, effort.pred, col = heat.colors(50),
400   xlab="Latitude", ylab="Longitude")
401 map(database = "state", regions = "CA", xlim =
402   range(fishing.data$LongDD)+c(-.1,.1), ylim =
403   range(fishing.data$LatDD)+c(-.1, .1), fill = TRUE, col =
404   rgb(0,100/256,0,.1), add = TRUE)
405 symbols(fishing.data$LongDD, fishing.data$LatDD, circles =
406   fishing.data$Effort, fg = rgb(0,0,0,.1), inches = .5, add = TRUE)
407 title("Effort")
408
409
410
411
412 #####
413 #                                     #
414 #   TOTAL EFFORT   #
415 #                                     #
416 #                                     #
417 #####
418
419 #different number of trips per year

```

```

420
421 N = 2731 #2003
422 #N = 3580 #2004
423 #N = 2313 #2005
424 #N = 3556 #2006
425 #N = 4114 #2008
426 #N = 4188 #2009
427 #N = 3790 #2010
428 #N = 4239 #2011
429 #N = 3787 #2012
430
431 pixel.ar = diff(kde$x[1:2]) * diff(kde$y[1:2])
432 #change year in prods
433 prods2003 = N * kde$z/sum(kde$z * pixel.ar) * pixel.ar * effort.pred
434
435 #change year in titles and withing image.plot
436 #par(mfrow=c(1,2))
437
438 #need heat scale the same on all years
439 image.plot(kde$x, kde$y, prods2003, col = heat.colors(50),
440 xlab="Latitude", ylab="Longitude", zlim=c(0,80000))
441 map(database = "state", regions = "CA", xlim =
442 range(fishing.data$LongDD)+c(-.1,.1), ylim =
443 range(fishing.data$LatDD)+c(-.1, .1), fill = TRUE, col =
444 rgb(0,100/256,0,.1), add = TRUE)
445 points(fishing.data$LongDD, fishing.data$LatDD, pch = 16, col =
446 rgb(0,0,0,.1), cex = .2)
447 title("Annual Effort (2003)")
448
449 ###zoomed in portion of the graph for better visualization
450 #image.plot(kde$x, kde$y, prods2003, col = heat.colors(50), xlim=c(-
451 121.0, -120.65), ylim=c(35, 35.4), xlab="Latitude",
452 ylab="Longitude")
453 #map(database = "state", regions = "CA", xlim = c(-121.0,-120.5),
454 ylim = c(35,35.4), fill = TRUE, col = rgb(0,100/256,0,.1), add =
455 TRUE)
456 #points(fishing.data$LongDD, fishing.data$LatDD, pch = 16, col =
457 rgb(0,0,0,.1), cex = .2)
458 #title("Annual Effort (2003)")
459
460
461
462 #####
463 # #
464 # Bootstrap #
465 # #
466 #####
467
468 set.seed(226)
469 B = 5000 # number of bootstraps
470 # total number of drops made by fishing company (monitored + not)
471
472 N = 2731 #2003
473 #N = 3580 #2004

```

```

474 #N = 2313 #2005
475 #N = 3556 #2006
476 #N = 4114 #2008
477 #N = 4188 #2009
478 #N = 3790 #2010
479 #N = 4239 #2011
480 #N = 3787 #2012
481
482 n = nrow(fishing.data)
483 kde.n = 100 # resolution of model
484 # fit kde just to get pixels and base pixels set
485 kde = with(fishing.data, kde2d(LongDD, LatDD, n=kde.n, h=.0155))
486 kde.lims = c(range(fishing.data$LongDD), range(fishing.data$LatDD))
487 image.plot(kde, col = heat.colors(12))
488 pixel.ar = diff(kde$x[1:2]) * diff(kde$y[1:2])
489
490
491 #change year in prods.array and within bootstrap loop
492 prods.array2012 = array(NA, c(kde.n, kde.n, B))
493 for(B.i in 1:B){
494   bootdata = fishing.data[sample(1:n, replace = TRUE),]
495   kde.b = with(bootdata, kde2d(LongDD, LatDD, n=kde.n, lims =
496     kde.lims, h=.0155))
497   gam.b = gam(Effort ~ s(LongDD, LatDD), data = bootdata)
498   pred.b = data.frame(expand.grid(LongDD = kde$x, LatDD = kde$y))
499   effort.b = matrix(predict(gam.b, pred.b), ncol = kde.n)
500   prods.array2012[, , B.i] = N * kde.b$z/sum(kde.b$z * pixel.ar) *
501     pixel.ar * effort.b
502 }
503
504
505
506 #change years
507 effort.mean2012 = apply(prods.array2012, c(1,2), mean)
508 effort.sd2012 = sqrt(apply(prods.array2012, c(1,2), var))
509
510
511 #save objects as .Rdata to avoid re-running bootstraps
512 #change years
513 save(prods.array2012, effort.mean2012, effort.sd2012,
514   file="2012Boot5000Data.Rdata")
515
516
517 ##determine max range for mean and sd to set limits for image.plot
518
519 #2003-2010
520 load(file="/Volumes/USB/Senior Project/2005Boot5000Data.Rdata")
521 #2011-2012
522 load(file="/Users/samdellinger/Documents/Cal Poly 2013-14/Senior
523   Project/2012Boot5000Data.Rdata")
524
525
526 range(effort.mean2003)
527

```

```

528 #2003 mean range= 0, 30385.87
529 #2004 mean range= 0, 33821.26
530 #2005 mean range= 0, 74563.47
531 #2006 mean range= 0, 49182.44
532 #2008 mean range= 0, 39058.74
533 #2009 mean range= 0, 79894.28
534 #2010 mean range= 0, 40188.94
535 #2011 mean range= 0, 65443.65
536 #2012 mean range= 0, 43507.75
537
538 ##max mean range = (0, 79894.28) so set zlim=c(0,80000)
539
540
541 range(effort.sd2003)
542
543 #2003 sd range= 0, 7955.95
544 #2004 sd range= 0, 5882.436
545 #2005 sd range= 0, 16477.52
546 #2006 sd range= 0, 8720.045
547 #2008 sd range= 0, 12063.52
548 #2009 sd range= 0, 21678.58
549 #2010 sd range= 0, 8773.712
550 #2011 sd range= 0, 1502.64
551 #2012 sd range= 0, 9763.391
552
553 ##max sd range = (0, 21678.58) so set zlim=c(0,22000)
554
555
556
557 #####
558 # #
559 # Images of Bootstrap Estiamtes #
560 # of Effort and Variability #
561 # #
562 #####
563
564
565 #change years in effort.mean and effort.sd
566 #par(mfrow=c(1,2))
567
568 image.plot(kde$x, kde$y, effort.mean2005, col = heat.colors(12),
569 xlab="Latitude", ylab="Longitude", zlim=c(0, 80000))
570 map(database = "state", regions = "CA", xlim =
571 range(fishing.data$LongDD)+c(-.1,.1), ylim =
572 range(fishing.data$LatDD)+c(-.1, .1), fill = TRUE, col =
573 rgb(0,100/256,0,.1), add = TRUE)
574 points(fishing.data$LongDD, fishing.data$LatDD, pch = 16, col =
575 rgb(0,0,0,.1), cex = .2)
576 title("Estimated Annual Effort (2005)")
577
578
579 image.plot(kde$x, kde$y, effort.sd2005, col = heat.colors(12),
580 xlab="Latitude", ylab="Longitude", zlim=c(0, 22000))
581 map(database = "state", regions = "CA", xlim =

```

```

582   range(fishing.data$LongDD)+c(-.1,.1), ylim =
583   range(fishing.data$LatDD)+c(-.1, .1), fill = TRUE, col =
584   rgb(0,100/256,0,.1), add = TRUE)
585 points(fishing.data$LongDD, fishing.data$LatDD, pch = 16, col =
586   rgb(0,0,0,.1), cex = .2)
587 title("Estimated SD of Annual Effort (2005)")
588
589
590
591
592 ##zoomed in portions of bootstrapped graphs
593 #change years in effort.mean and effort.sd
594 #par(mfrow=c(1,2))
595
596 image.plot(kde$x, kde$y, effort.mean2003, col = heat.colors(12),
597   xlim = c(-121.0,-120.65), ylim = c(35,35.4), xlab="Latitude",
598   ylab="Longitude")
599 map(database = "state", regions = "CA", xlim = c(-121.0,-120.65),
600   ylim = c(35,35.4), fill = TRUE, col = rgb(0,100/256,0,.1), add =
601   TRUE)
602 points(fishing.data$LongDD, fishing.data$LatDD, pch = 16, col =
603   rgb(0,0,0,.1), cex = .2)
604 title("Estimated Annual Effort (2003)")
605
606
607 image.plot(kde$x, kde$y, effort.sd2003, col = heat.colors(12), xlim
608   = c(-121.0,-120.65), ylim = c(35,35.4), xlab="Latitude",
609   ylab="Longitude")
610 map(database = "state", regions = "CA", xlim = c(-121.0,-120.65),
611   ylim = c(35,35.4), fill = TRUE, col = rgb(0,100/256,0,.1), add =
612   TRUE)
613 points(fishing.data$LongDD, fishing.data$LatDD, pch = 16, col =
614   rgb(0,0,0,.1), cex = .2)
615 title("Estimated SD of Annual Effort (2003)")
616
617
618
619
620
621 ###DIFFERENCE IN (average) ANNUAL EFFORT pre-mpa and post-mpa
622
623 #total effort per year
624 t2003 = mean(apply(prods.array2003, 3, sum))
625 t2004 = mean(apply(prods.array2004, 3, sum))
626 t2005 = mean(apply(prods.array2005, 3, sum))
627 t2006 = mean(apply(prods.array2006, 3, sum))
628
629 t2008 = mean(apply(prods.array2008, 3, sum))
630 t2009 = mean(apply(prods.array2009, 3, sum))
631 t2010 = mean(apply(prods.array2010, 3, sum))
632 t2011 = mean(apply(prods.array2011, 3, sum))
633 t2012 = mean(apply(prods.array2012, 3, sum))
634
635

```

```

636 #difference in total effort pre and post mpas
637 d.hat = .2 * (t2008+t2009+t2010+t2011+t2012) - .25 *
638     (t2003+t2004+t2005+t2006)
639
640
641 #estimated variances of total effort
642 s.hat.2003 = var(apply(prods.array2003, 3, sum))
643 s.hat.2004 = var(apply(prods.array2004, 3, sum))
644 s.hat.2005 = var(apply(prods.array2005, 3, sum))
645 s.hat.2006 = var(apply(prods.array2006, 3, sum))
646
647 s.hat.2008 = var(apply(prods.array2008, 3, sum))
648 s.hat.2009 = var(apply(prods.array2009, 3, sum))
649 s.hat.2010 = var(apply(prods.array2010, 3, sum))
650 s.hat.2011 = var(apply(prods.array2011, 3, sum))
651 s.hat.2012 = var(apply(prods.array2012, 3, sum))
652
653
654 #estimated variance for the difference in total effort
655 #(1/5)^2 = .04    (1/4)^2 = .0625
656 s.hat.d = sqrt(.04*s.hat.2003 + .04*s.hat.2004+ .04*s.hat.2005+
657     .04*s.hat.2006+ .0625*s.hat.2008+ .0625*s.hat.2009+
658     .0625*s.hat.2010+ .0625*s.hat.2011+ .0625*s.hat.2012)
659
660
661 #create confidence interval
662 d.ll = d.hat - (1.96 * s.hat.d)
663 d.ul = d.hat + (1.96 * s.hat.d)
664
665
666 #summary of parts to confidence interval
667 d.hat
668 s.hat.d
669 d.ll
670 d.ul

```

B. Record of Hours

| Date | Start Time | End Time | Hours |
|----------|------------|----------|-------|
| 9/30/13 | 10:30 AM | 11:30 AM | 1 |
| 10/4/13 | 10:00 AM | 12:00 PM | 2 |
| 10/9/13 | 11:00 AM | 12:00 PM | 1 |
| 10/24/13 | 2:00 PM | 3:00 PM | 1.5 |
| 10/25/13 | 10:00 AM | 12:00 PM | 2 |
| 10/26/13 | 1:30 PM | 2:30 PM | 1 |
| 10/28/13 | 11:30 AM | 12:00 PM | 0.5 |
| 11/1/13 | 10:00 AM | 11:00 AM | 1 |
| 11/20/13 | 11:00 AM | 1:00 PM | 2 |
| 11/23/13 | 9:00 AM | 11:00 AM | 2 |

| | | | |
|----------|----------|----------|-----|
| 12/1/13 | 7:00 PM | 7:30 PM | 0.5 |
| 12/4/13 | 11:00 AM | 12:00 PM | 1 |
| 12/7/13 | 12:00 PM | 2:00 PM | 2 |
| 12/11/13 | 11:00 AM | 12:00 PM | 1 |
| 1/8/14 | 11:00 AM | 11:00 AM | 1 |
| 1/9/14 | 12:30 PM | 2:00 PM | 1.5 |
| 1/14/14 | 1:00 PM | 2:00 PM | 1 |
| 2/4/14 | 1:00 PM | 2:00 PM | 1 |
| 2/5/14 | 9:00 AM | 10:00 AM | 1 |
| 2/6/14 | 10:00 AM | 11:00 AM | 1 |
| 2/7/14 | 11:00 AM | 12:00 PM | 1 |
| 2/20/14 | 9:00 AM | 10:00 AM | 1 |
| | 7:30 PM | 9:30 PM | 2 |
| 2/21/14 | 6:30 PM | 9:30 PM | 3 |
| 3/4/14 | 9:30 AM | 10:30 AM | 1 |
| 3/6/14 | 12:00 PM | 3:30 PM | 3.5 |
| 3/13/14 | 9:00 AM | 10:00 AM | 1 |
| 3/17/14 | 6:00 PM | 10:00 PM | 4 |
| 3/18/14 | 9:00 AM | 10:00 AM | 1 |
| 4/3/14 | 11:30 AM | 1:00 PM | 1.5 |
| 4/7/14 | 3:00 PM | 5:00 PM | 2 |
| 4/10/14 | 9:00 AM | 10:00 AM | 1 |
| 4/16/14 | 1:00 PM | 4:00 PM | 3 |
| 4/21/14 | 9:00 AM | 12:00 PM | 3 |
| 4/24/14 | 10:00 AM | 11:00 AM | 1 |
| | 12:00 PM | 2:00 PM | 2 |
| 4/28/14 | 3:00 PM | 7:00 PM | 4 |
| 5/9/14 | 10:00 AM | 2:30 PM | 4.5 |
| 5/13/14 | 10:00 AM | 12:30 PM | 2.5 |
| 5/15/14 | 10:00 AM | 11:00 AM | 1 |
| 5/20/14 | 11:30 AM | 11:00 PM | 1.5 |
| 5/22/14 | 10:00 AM | 11:00 AM | 1 |
| 5/25/14 | 9:00 AM | 12:00 PM | 3 |
| 5/26/14 | 10:00 AM | 1:30 PM | 3.5 |
| | 5:00 PM | 10:30 PM | 5.5 |
| 5/27/14 | 12:00 PM | 1:30 PM | 1.5 |
| 28-May | 7:00 PM | 12:00 PM | 5 |
| 5/29/14 | 10:00 AM | 12:00 PM | 2 |
| | 7:30 PM | 10:00 PM | 2.5 |
| 5/30/14 | 11:00 AM | 12:30 PM | 1.5 |
| 6/2/14 | 7:00 PM | 9:30 PM | 2.5 |

| | | | |
|--------|----------|----------|-----|
| 6/3/14 | 11:00 AM | 4:00 PM | 5 |
| 6/4/14 | 12:30 PM | 2:00 PM | 1.5 |
| 6/7/14 | 9:30 AM | 11:00 PM | 1.5 |
| 6/8/14 | 4:30 PM | 8:00 PM | 3.5 |
| | | | |
| | | | |
| Total: | | | 109 |

VI. Works Cited

Breheny, Patrick. *Kernel density estimation*,

<http://web.as.uky.edu/statistics/users/pbreheny/621/F12/notes/10-18.pdf>

California Marine Protected Areas, *Central Coast MPA Region*.

<http://www.californiampas.org/pages/regions/centralcoast.html> (January 2014).

Clark, Michael., *Generalized Additive Models*, Center for Social Research University of Notre Dame,

Page 7, <http://www3.nd.edu/~mclark19/learn/GAMS.pdf>

Zucchini, Walter., *Part I: Kernel Density Estimation*, Applied Smoothing Techniques,

http://isc.temple.edu/economics/Econ616/Kernel/ast_part1.pdf